

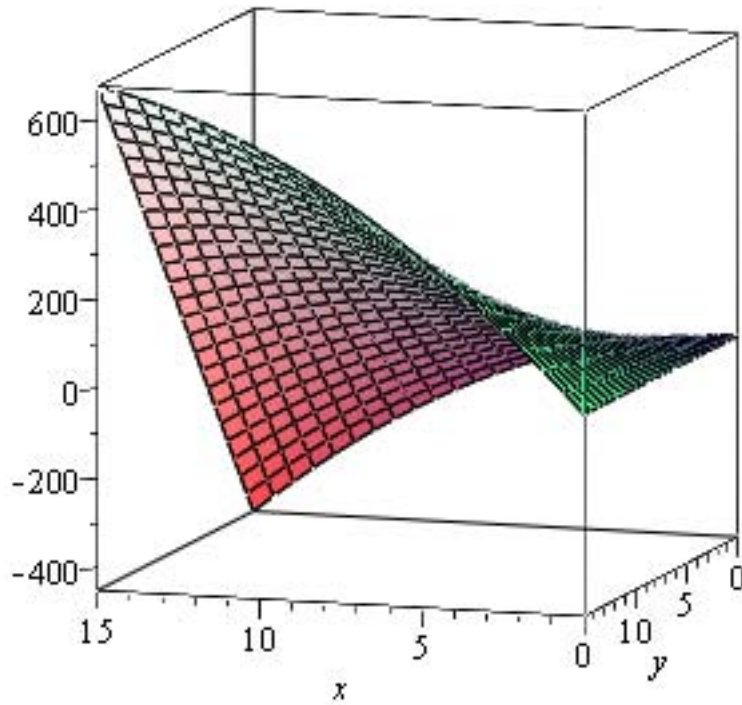
```
> restart : # SimpleContinuous.mw
```

```
> f := (x, y) → -2·x2 + 5·x·y
```

```
f := (x, y) → -2 x2 + 5 x y
```

```
> plot3d(f(x, y), x=0..15, y=0..15, axes = boxed)
```

(1)



```
> with(Optimization)
```

```
[ImportMPS, Interactive, LPSolve, LSSolve, Maximize, Minimize, NLPsolve, QPSolve]
```

(2)

```
> NLPsolve(f(x, y), x=0..15, y=0..15, maximize)
```

```
[675., [x=15., y=15.]]
```

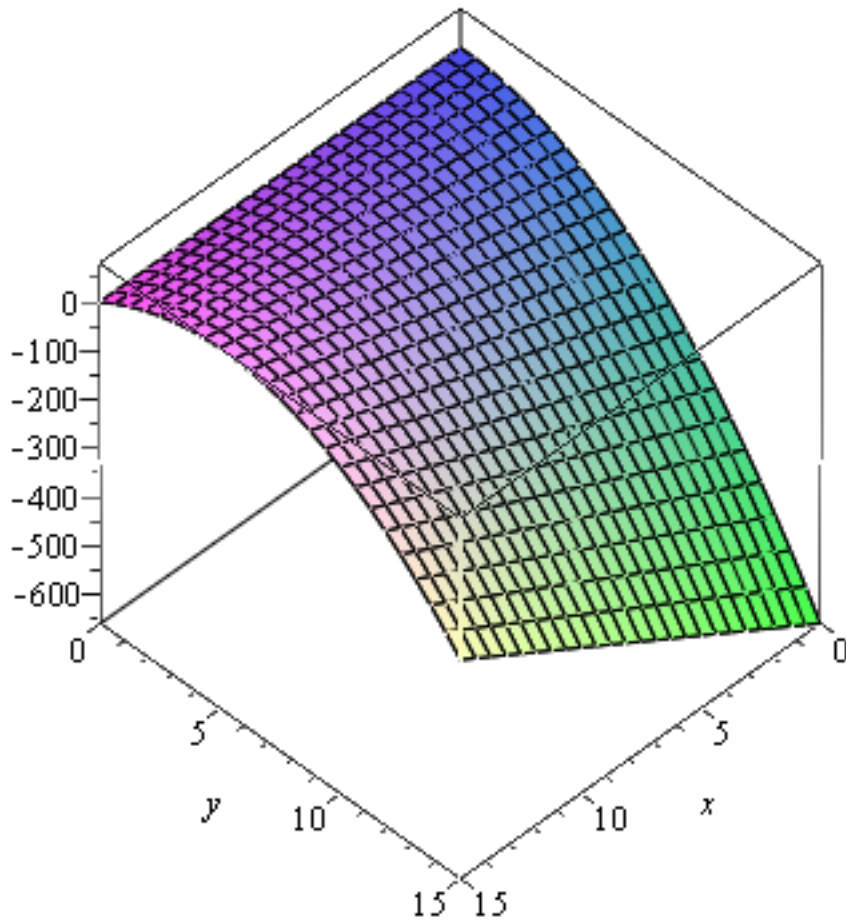
(3)

```
> g := (x, y) → -3·y2 + 2·x·y + y
```

```
g := (x, y) → -3 y2 + 2 x y + y
```

(4)

```
> plot3d(g(x, y), x=0..15, y=0..15, axes = boxed)
```



```
> NLPsolve(g(x, y), x=0..15, y=0..15, maximize)
      [80.0833333333333286, [x=15., y=5.16666666666666606]]
```

(5)

```
> fx := diff(f(x, y), x); gy := diff(g(x, y), y)
      fx := -4x + 5y
      gy := -6y + 2x + 1
```

(6)

```
> solve({fx, gy}, {x, y})
      {x = 5/14, y = 2/7}
```

(7)

```
> assign(%)
> x, y
      5/14, 2/7
```

(8)

```
> f(x, y); g(x, y)
      25
      98
      12
      49
```

(9)

```
>
```

